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Air, Water and Soil Pollution Science and Technology



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Indoor Air Quality

Control, Health Implications and Challenges



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Chapter 3

Computational Study and Experimental Validation of Heat Ventilation in a Box Prototype

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Abstract

In this chapter, the impact of the numerical parameters on the heat ventilation was studied in a box prototype. Particularly, a computational study and an experimental validation have been developed to compare the standard $k\text{-}\omega$ turbulence model, the BSL $k\text{-}\omega$ turbulence model, the RNG k-\$\varepsilon\$ turbulence model and the Realizable k-\$\varepsilon\$ turbulence model. From the obtained results, it is noticed that the aerodynamic characteristics present the same emergence nevertheless the maximum values depend on the turbulence model. Particularly, it has been noted that the value founded with the standard k-\$\varepsilon\$ turbulence model is nearest to the experimental

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results. This study tends to show that the standard $k\text{-}\omega$ turbulence model is the most efficient to study the air flow in the box prototype. For this model, the meshing effect on the CFD results was studied to choose the adequate mesh with a minimum calculated time. The numerical results were compared using experimental results developed in our laboratory. The good agreements confirm the numerical method.

Nomenclature

A_0	Model constant
A_s	Model constant
C_1	Model constant
$C_{1\epsilon}$	Constant of the k-ε turbulence model (dimensionless)
$C_{2\epsilon}$	Constant of the k-ε turbulence model (dimensionless)
C_{μ}	Constant of the k-ɛ turbulence model (dimensionless)
E	Total energy (J)
F_{i}	Force components on the i direction (N)
G_k	Generation of the turbulent kinetic energy (kg.m ⁻¹ .s ⁻³)
G_b	Generation of turbulence kinetic energy (kg.m ⁻¹ .s ⁻³)
G_{v}	Production of turbulent viscosity (kg.m.s ⁻²)
$G_{\boldsymbol{\omega}}$	Generation of the dissipation rate of the turbulent kinetic energy (kg.m ⁻¹ .s ⁻³)
Н	
	Height (m)
h	Thermal enthalpy (J.kg ⁻¹)
k	Turbulent kinetic energy (m ² .s ⁻²)
1	Length (m)
p	Pressure (Pa)
P _r	Prandt number
Q _H	Heat source or sink per unit volume (kg.m ⁻¹ .s ⁻³)
q_{i}	Diffusive heat flux (J)
Re	Reynolds number (dimensionless)
R_k	Constant of the k-ω turbulence model (dimensionless)
R_{ω}	Constant of the k-ω turbulence model (dimensionless)
S	Scalar measure of the deformation tensor
S_{i}	Mass-distributed (kg.m ⁻² .s ⁻²)
S_{ij}	Mean rate-of-strain tensor (s ⁻¹)
S_{ω}	Source terms of the specific dissipation rate of the turbulent
	kinetic energy (kg.m ⁻¹ .s ⁻³)

 S_k Source terms of the turbulent kinetic energy (kg.m⁻¹.s⁻³) S_{ϵ} Source terms of the dissipation rate of the turbulent kinetic energy (kg.m⁻¹.s⁻³) Т Temperature (K) Time (s) t Velocity components (m.s⁻¹) u Fluctuating velocity components (m.s⁻¹) u_i V Magnitude velocity (m.s⁻¹) Cartesian coordinate (m) Xi Cartesian coordinate (m) X Cartesian coordinate (m) y Fluctuating dilatation in compressible turbulence (kg.m⁻¹.s⁻ Y_{M} 3) Y_k Turbulence dissipation of k Yω Turbulence dissipation of ω Cartesian coordinate (m) 7. U Free-stream velocity (m/s) Constant of the k-\varepsilon turbulence model (dimensionless) η_0 Constant of the k-ω turbulence model (dimensionless) α_0 Constant of the k-ω turbulence model (dimensionless) α_{∞} Constant of the k-ω turbulence model (dimensionless) α^*_{∞} Kronecker delta function (dimensionless) δ_{ii} β Constant of the k-\varepsilon turbulence model (dimensionless) Dissipation rate of the turbulent kinetic energy (m².s⁻³) 3 Dynamic viscosity (Pa.s) μ Turbulent viscosity (Pa.s) μ_t Effective viscosity (Pa.s) μ_{eff} Specific dissipation rate (s⁻¹) ω Density (kg.m⁻³) ρ Constant of the k-ω turbulence model (dimensionless) β_i Constant of the k-\varepsilon turbulence model (dimensionless) σ_k Constant of the k-\varepsilon turbulence model (dimensionless) σ_{ϵ} Turbulent Prandtl number for k (dimensionless) σ_k Turbulent Prandtl number for ω (dimensionless) σ_{ω} Viscous shear stress tensor (Pa) τ_{ii} Deviatoric stress tensor (Pa) $(\tau_{ij})_{eff}$

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Equivalence ratio (dimensionless)

Effective diffusivity of k

Φ

 Γ_k

 $\begin{array}{ll} \Gamma_{\omega} & & \text{Effective diffusivity of } \omega \\ \Omega & & \text{Swirl number (dimensionless)} \\ \Omega_{ij} & & \text{Rate of rotation tensor } (s^{\text{-}1}) \end{array}$

Keywords: heat ventilation, box prototype, turbulence model effect, experimental validation, CFD

1. Introduction

Heat ventilation by solar energy is used for wide range applications, such as hospitals, residential and commercial buildings. One of the chief benefits the solar ventilation is the reduction of the energy consumption by using renewable sources [1-7]. The mechanism of Heat ventilation has been investigated by many researchers. In particular, Driss et al. [1] investigated thermal comfort evaluation and the heat ventilation in a living room. In other Teodosiu et al. [8] presented experimental-numerical comparisons to give the precision of a CFD model. Du et al. [9] conducted experimental measurements to present the characteristics of a Chinese house. Homod et al. [10] studied and proposed a new system by coupling reasons of internal conditions that are influenced by the outdoor environment. Terrados and Moreno [11] integrated the architectural concepts with energy efficient. Yasa [12] analysed the inside regions and the surrounding areas of education buildings and performed the microclimatic comfort. Premrov et al. [13] studied a single storey house wood frame case for objective to avoid the last energy. Johnston [14] predicted and measured performance of the building fabric in new build dwellings. Chan et al. [15] modeled a building of 21 floors by using Energy plus. The results of simulations indicate that the apartments flat presents satisfactory periods for the environment. Ibrahim et al. [16] planned technical coating projection. The proposed mathematical model was compared with experimental results. Nam and Chae [17] developed an optimal design of the grounding by using a numerical method. Alam et al. [18] improves a method of releasing heat from the building to reduce the energy demand of the building in a tropical environment. Rode [19] illustrated global relations to highlight the building performance. Han et al. [20] investigated hybrid solar energy system. A general view of the architectural envelope designs and innovative system was presented. Watson [21] reviewed design quality research on buildings in relation to users. Sailor et al. [22] describe the system use implications that lead to building energy of green roof design decisions.

From these different anterior works, it has been noted that the design of buildings based on the reduction of the energy consumed. For thus, we have involved the study of the heat ventilation in a box prototype. Particularly, we have considered the turbulence models effect to choose the most effective model. The numerical results obtained in this work are validated via a box prototype realized in our LASEM laboratory.

2. Box Prototype System

Figure 1 depicts the physical domain of the considered box prototype. The box is characterized by a 0.22 m of height, 0.2 m of width and 0.3 m of length. Both square holes are localized at the same wall of the box. It has the same edge which is equal to 0.02 m, while it has different distance from the bottom wall of the box. The down hole is situated with a distance equal to $h_1 = 0.05$ m from the bottom wall, which is used to receive the air flow coming from the outside of the box prototype. However, the top hole is responsible on the evacuation of the air flow from the box to the surrounding air [1]. It is situated from the box base with a distance equal to $h_2 = 0.18$ m.

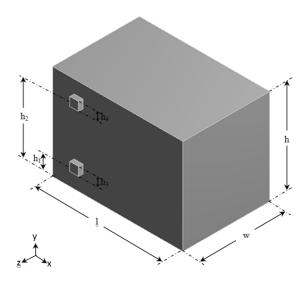


Figure 1. 3D view of the prototype.

3. Numerical Model

3.1. Boundary Conditions

The applied boundary conditions of the considered system are shown in Figure 2. The hot airflow enters to the box prototype through the down hole which is assumed as the inlet system. The velocity and the temperature at the inlet are respectively equal to V = 3.4 m.s-1 and T = 310 K. After the fluid recirculation inside the box, the airflow exits the system through a top hole with a pressure outlet value identical to the ambient static pressure. A no slip wall is applied for the outer walls of the domain.

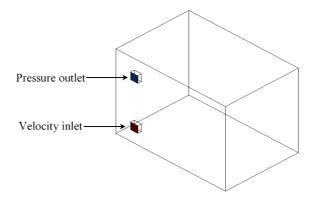


Figure 2. Boundary conditions.

3.2. Meshing

The meshing is an amportant step in the simulation procudure which affects directly the accuracy of the computantional findings. Then, a meshing analysis is required to minimize the error calculation. In the present study, the employed mesh density is taken from an anterior meshing analysis [23-32] which compares different meshing cases with our experimental data. The meshing choice is based on both accuracy and calculation time [33]. Figure 3 shows a view of the used optimal mesh with a tetrahedral volume cells. The 3D computantional domain is characterized by 167400 cells and 64312 nodes.

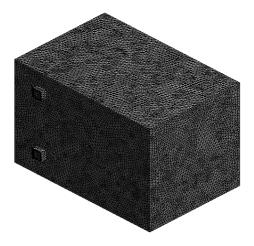


Figure 3. Meshing.

3.3. Mathematical Formulation

Table 1. Constants of the turbulence models

(a) Standard k- ε model

$C_{1\epsilon}$	$C_{2\varepsilon}$	$C_{\rm u}$	σ_k	σ_{ϵ}
1.44	1.92	0.09	1.0	1.3

(b) RNG k- ε model

C_1	$C_{2\epsilon}$	β	
1.44	1.92	0.012	4.38

(c) Realizable k- ε model

C_1	$C_{2\varepsilon}$	σ_k	σ_{ϵ}
1.44	1.9	1.0	1.2

(d) Standard k- ω model

α_0	α_{∞}	α^*_{∞}	R_{ω}	R_k	σ_k	σ_{ω}
1/9	1.9	1.0	2.95	6.0	2.0	2.0

Table 1. (Continued)

(e) BSL k-ω model

$\sigma_{k,1}$	$\sigma_{k,2}$	$\sigma_{\omega,1}$	σω,2	$\beta_{i,1}$	$\beta_{i,2}$
2.0	1.0	2.0	1.168	0.075	0.0828

(f) SST k- ω model

$\sigma_{k,1}$	$\sigma_{k,2}$	σω,1	σω,2	$\beta_{i,1}$	$\beta_{i,2}$	$a_{\scriptscriptstyle 1}$
1.176	1.0	2.0	1.168	0.075	0.0828	0.31

The considered governing equations are the continuity equation, the momentum equations and the energy equation [34-26]. Taking a time average yields in the instantaneous equations, the Reynolds-averaged Navier-Stokes (RANS) equations can be written as follows:

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i) = 0 \tag{1}$$

$$\frac{\partial}{\partial t}(\rho u_i) + \frac{\partial}{\partial x_j}(\rho u_i u_j) = -\frac{\partial p}{\partial x_j} \left[\mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial j_i}{\partial x_i} - \frac{2}{3} \right) \right] + \frac{\partial}{\partial x_j} (-\rho \overline{u_i' u_j'}) F_i$$
(2)

To close equation (2), these Reynolds stresses $-\rho \overline{u_i' u_j'}$ must be modeled by using the Boussinesq hypothesis, written as follows:

$$-\rho \overline{u_i' u_j'} = \mu_t \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) - \frac{2}{3} \left(\rho k + \mu_t \frac{\partial u_k}{\partial x_k} \right) \delta_{ij}$$
(3)

The energy equation is expressed as follows:

$$\frac{\partial}{\partial t}(\rho E) + \frac{\partial}{\partial x_{i}} \left[u_{i}(\rho E + p) \right] = \frac{\partial}{\partial x_{j}} \left[\left(k + \frac{c_{p} \mu_{t}}{Pr_{t}} \right) \frac{\partial T}{\partial x_{j}} + u_{i} \left(\tau_{ij} \right)_{eff} \right] + S_{h}$$
(4)

where K is the thermal conductivity and E is the total energy. $\left(\tau_{ij}\right)_{eff}$ is the deviatoric stress tensor and is written as follows:

$$\left(\tau_{ij}\right)_{\text{eff}} = \mu_{\text{eff}} \left(\frac{\partial u_{j}}{\partial x_{i}} + \frac{\partial u_{i}}{\partial x_{j}}\right) - \frac{2}{3}\mu_{\text{eff}} \frac{\partial u_{k}}{\partial x_{k}} \delta_{ij}$$
(5)

The standard model k- ϵ is modeling by both transport equations of the turbulent kinetic energy k and its dissipation rate ϵ . These equations are obtained from the following expressions:

$$\frac{\partial}{\partial t}(\rho k) + \frac{\partial}{\partial x_{j}}(\rho k u_{i}) = \frac{\partial}{\partial x_{j}} \left[\left(\mu + \frac{\mu_{t}}{\sigma_{k}} \right) \frac{\partial k}{\partial x_{j}} \right] + G_{k} + G_{b} - \rho \varepsilon - Y_{M} + S_{k}$$
(6)

$$\frac{\partial}{\partial t}(\rho \varepsilon) + \frac{\partial}{\partial x_{i}}(\rho \varepsilon u_{i}) = \frac{\partial}{\partial x_{j}} \left[\left(\mu + \frac{\mu_{t}}{\sigma_{\varepsilon}} \right) \frac{\partial \varepsilon}{\partial x_{j}} \right] + C_{1\varepsilon} \frac{\varepsilon}{k} \left(G_{k} + C_{3\varepsilon} G_{b} \right) - C_{2\varepsilon} \frac{\varepsilon^{2}}{k} + S_{\varepsilon}$$
(7)

 $\mu_{_{t}}$ is the turbulent viscosity computed from the combination of k and $\epsilon :$

$$\mu_{t} = \rho C_{\mu} \frac{k^{2}}{\varepsilon} \tag{8}$$

Table 1 (a) illustrates the different constants employed in the k- ϵ turbulence model.

The RNG k-ε model presents similarity with the standard k-ε turbulence model:

$$\frac{\partial}{\partial t}(\rho k) + \frac{\partial}{\partial x_{i}}(\rho k u_{i}) = \frac{\partial}{\partial x_{j}} \left(\alpha_{k} \mu_{eff} \frac{\partial k}{\partial x_{j}}\right) + G_{k} + G_{b} - \rho \varepsilon - Y_{M} + S_{k}$$
(9)

$$\frac{\partial}{\partial t} (\rho \varepsilon) + \frac{\partial}{\partial x_{i}} (\rho \varepsilon u_{i}) = \frac{\partial}{\partial x_{j}} \left(\alpha_{\varepsilon} \mu_{\text{eff}} \frac{\partial \varepsilon}{\partial x_{j}} \right) + C_{1\varepsilon} \frac{\varepsilon}{k} (G_{k} + C_{3\varepsilon} G_{b}) - C_{2\varepsilon} \rho \frac{\varepsilon^{2}}{k} - R_{\varepsilon} + S_{\varepsilon}$$
(10)

In these conditions, we have to write:

$$d\left(\frac{\rho^2 k}{\sqrt{\epsilon \mu}}\right) = 1.72 \frac{\hat{v}}{\sqrt{\hat{v}^3 - 1 + C_v}} d\hat{v}$$
(11)

$$\hat{\mathbf{v}} = \frac{\mu_{\text{eff}}}{\mu} \tag{12}$$

The difference between the RNG and the standard k-ε turbulence models consists in the addition of this term:

$$R_{\varepsilon} = \frac{C_{\mu} \rho \eta^{3} (1 - \eta / \eta_{0})}{1 + \beta \eta^{3}} \frac{\varepsilon^{3}}{k}$$
(13)

where:

$$\eta = S \frac{k}{\varepsilon} \tag{14}$$

$$S = \sqrt{2S_{ij}S_{ij}} \tag{15}$$

Table 1 (b) illustrates the different constants employed in the RNG k- ϵ turbulence model.

In the realizable k- ϵ turbulence model, the transport equation is giving as follows:

$$\frac{\partial}{\partial t}(\rho k) + \frac{\partial}{\partial x_{j}}(\rho k u_{j}) = \frac{\partial}{\partial x_{j}} \left[\left(\mu + \frac{\mu_{t}}{\sigma_{k}} \right) \frac{\partial k}{\partial x_{j}} \right] + G_{k} + G_{b} - \rho \varepsilon - Y_{M} + S_{k}$$
(16)

$$\frac{\partial}{\partial t}(\rho\epsilon) + \frac{\partial}{\partial x_{_{j}}}(\rho\epsilon u_{_{j}}) = \frac{\partial}{\partial x_{_{j}}} \left[\left(\mu + \frac{\mu_{_{t}}}{\sigma_{_{\epsilon}}} \right) \frac{\partial\epsilon}{\partial x_{_{j}}} \right] + \rho C_{_{1}} S\epsilon - \rho C_{_{2}} \frac{\epsilon^{2}}{k + \sqrt{v\epsilon}} + C_{_{1\epsilon}} \frac{\epsilon}{k} C_{_{3\epsilon}} G_{_{b}} + S_{_{\epsilon}}$$

$$(17)$$

where:

$$C_1 = \max \left[0.43 \frac{\eta}{\eta + 5} \right] \tag{18}$$

As other k- ϵ turbulence models, the turbulent viscosity is calculated as follows:

$$\mu_{t} = \rho C_{\mu} \frac{k^{2}}{\varepsilon} \tag{19}$$

The difference between the realizable k- ε , the standard k- ε and the RNG k- ε turbulence models consists on the calculation of C_{μ} as:

$$C_{\mu} = \frac{1}{A_0 + A_s \frac{kU^*}{\varepsilon}}$$
(20)

Table 1 (c) illustrates the different constants employed in the realizable k- ϵ model.

In the k- ω standard turbulence model, the transport equations of the turbulent kinetic energy k and the specific dissipation rate ω are written as follows:

$$\frac{\partial}{\partial t} (\rho k) + \frac{\partial}{\partial x_i} (\rho k u_i) = \frac{\partial}{\partial x_j} \left(\Gamma_{\omega} \frac{\partial k}{\partial x_j} \right) + G_k + Y_k + S_k$$
(21)

$$\frac{\partial}{\partial t} (\rho \omega) + \frac{\partial}{\partial x_{i}} (\rho \omega u_{i}) = \frac{\partial}{\partial x_{j}} \left(\Gamma_{\omega} \frac{\partial k}{\partial x_{j}} \right) + G_{\varpi} + Y_{\omega} + S_{\omega}$$
(22)

Table 1 (d) illustrates the different constants employed in the $k\text{-}\omega$ turbulence model.

The BSL (Baseline) k-ω turbulence model presents a similar form:

$$\frac{\partial}{\partial t}(\rho k) + \frac{\partial}{\partial x_i}(\rho k u_i) = \frac{\partial}{\partial x_j} \left(\Gamma_k \frac{\partial k}{\partial x_j} \right) + G_k + Y_k + S_k$$
(23)

$$\frac{\partial}{\partial t} (\rho \omega) + \frac{\partial}{\partial x_{i}} (\rho \omega u_{i}) = \frac{\partial}{\partial x_{j}} \left(\Gamma_{k} \frac{\partial \omega}{\partial x_{j}} \right) + G_{\omega} + Y_{\omega} + D_{\omega} + S_{\omega}$$
(24)

Constants of the BSL k-ω model are presented in Table 1 (e).

Table 1 (e) illustrates the different constants of the BSL k- ω turbulence model.

To make the SST k- ω turbulence model more accurate, it includes all the refinements of the BSL k- ω turbulence model. Constants of the SST turbulence k- ω model are presented in Table 1 (f).

3.4. Choice of the Turbulence Model

The effect of the turbulence model on the numerical results have been studied in this section in order to achieve the adequate model. In fact, different turbulence models were studied using the software "Ansys Fluent 17.0" for solving the governing equations. Particularly, we have compared the BSL k- ω turbulence model, the standard k- ω turbulence model, the standard k- ϵ turbulence model, the SST k-ω turbulence model, the Realizable k-ε turbulence model and the RNG k-ɛ turbulence model. In the viewed direction set by the intersection of the two planes x = 0.06 m and z = -0.005 m, the superposition of the experimental results with the velocity profiles for the different turbulence models are presented in Figure 4. According to these results, the same profiles of the velocity have been observed and the values take down of the turbulence model. Particularly, it has been observed that the value founded with the experimental data is nearest to the standard k-ω tubulence model results. This study tends to show that the standard k-ω turbulence model is the most efficient to model the air flow in the present application. Therefore, the overall error designed between the numerical and the experimental data is equal to 5%. Thus, we found that the numerical results are in good agreement with the experimental data which confirms the validity of the numerical method.

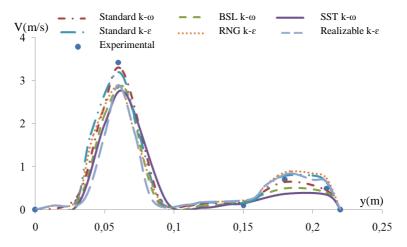


Figure 4. Velocity profiles in the direction defined by z = -0.005 m and x = 0.06 m.

4. Results and Discussion

The distribution of the velocity fields, the temperature, the total pressure, the turbulent kinetic energy and the turbulent viscosity are studied in this section. In the present study, the employed Reynolds number is equal to Re = 5100.

4.1. Velocity Fields

The distribution of the velocity fields in the plane defined by $x=0.06\,\mathrm{m}$ is shown in Figure 5 for the different studied turbulence models. From these results, it has been observed a discharge zone at the box inlet hole in all cases with average velocity equal to $V=3.4\,\mathrm{m.s^{-1}}$. The inlet flow barges into the reverse wall of the box and then it moves inside the box with a turbulent behavior to evacuate through the top hole. Otherwise, both axial directions of the airflow are seen inside the box. The recirculation zone appeared in the whole area of the box is created by the change of the flow direction, specially by the first ascending flow. Meanwhile, the weak zone showed in the down area of the box is created by the second descending flow. In these conditions, the averaged velocity presents a very low value in the whole system when exclude the values in the discharge area which reaches $V=1.3\,\mathrm{m.s^{-1}}$. The comparison between the different turbulence models affirms that the choice of

the adequate model presents a straight effect on the velocity fields. Particularly, it is noticed that the recirculation zone has been involved by the turbulence model choice. In this situation, the maximum value of the averaged velocity is obtained for the SST k- ω turbulence model and it reachs V=4.75 m.s⁻¹. However, the minimum value is founded for the standard k- ε turbulence model and it reachs V=4.42 m.s⁻¹.

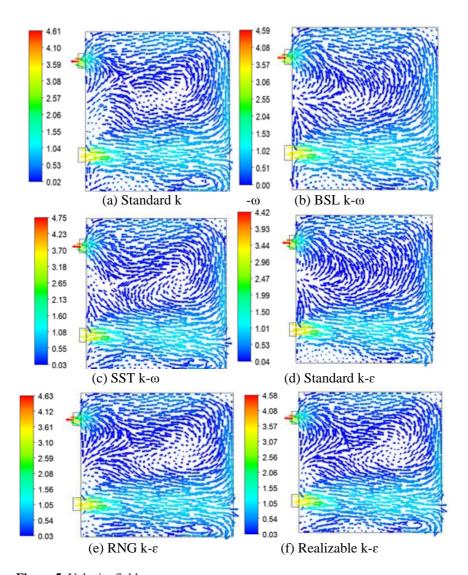


Figure 5. Velocity fields.

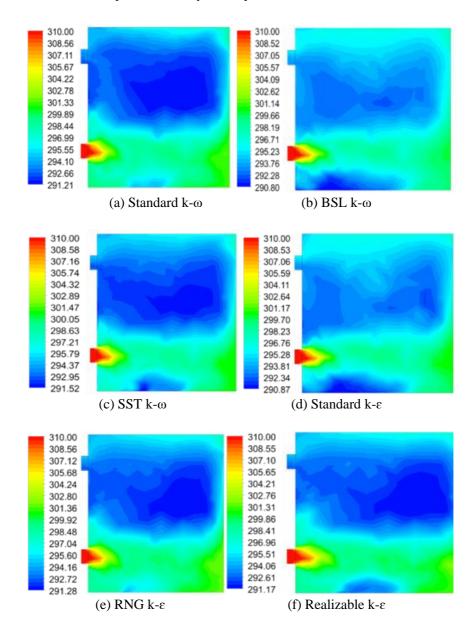


Figure 6. Distribution of the temperature.

4.2. Temperature

The distribution of the air temperature at t=2 s and in the plane defined by x=0.06 m is shown in Figure 6 for the considered turbulence models. According to these results, it has been observed that the temperature at the hole inlet is equal to T=310 K while, it slightly decreases in the discharge area, at the hole inlet. However, the temperature decreases above the discharge area due to the recirculation region appeared into the whole area of the box prototype. Otherwise, the air temperature decreases gradually to reaches the minimum values at the system outlet with a value equal to T=290 K. The comparison between the founded results affirms that the choice of the turbulence model presents a straight effect on the temperature distribution. Particularly, it has been noted that the minimum value of the temperature is obtained in the hole outlet for the BSL k- ω turbulence model and it is equal to T=290.8 K. However, the maximum value of the temperature reaches T=291.5 K for the SST k- ω turbulence model.

4.3. Total Pressure

Figure 7 shows the distribution of the total pressure in the plane defined by x=0.06 m for all considered turbulence models. From these results, it is clear that a compression zone appears in the down hole of the box prototype for all cases. In fact, the total pressure decreases in the expulsion area, produced from the system inlet and attacked until the reverse wall of the box. This fact can be clarified by the recirculation zone showed at the whole area of the box prototype. From that point onward, the total pressure increases to reaches the peak value at the opposite wall. However, a depression zone is appeared at the top hole in the system outlet for all cases. A comparison between the different turbulence models gives that the turbulence model presents a straight effect on the distribution of the total pressure. In fact, it has been noted that the maximum value of the total pressure is founded for the standard k- ω and the SST k- ω turbulence models and presents a value equal to p = 101342 Pa. This value decreases slightly for the other turbulence models and reaches the minimum value equal to p = 101340 Pa, for the standard k- ε turbulence model.

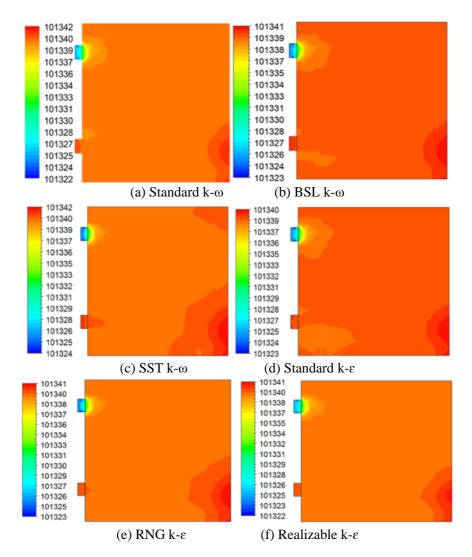


Figure 7. Distribution of the total pressure.

4.4. Turbulent Kinetic Energy

Figure 8 depicts the distribution of the turbulent kinetic energy in the plane defined by x = 0.06 m for the considered turbulence models. From these results, it can be seen that the turbulent kinetic energy presents a small value at the system inlet. In mean time, the turbulent kinetic energy increases

gradually in the expulsion area created in the down hole of the box. Otherwise, it has been observed that the maximum values of the turbulent kinetic energy appear at the discharge area near the reverse wall and at the top hole of the box outlet. As causes the other air proprieties, this fact is owing to the recirculation zone in the whole area of the box.

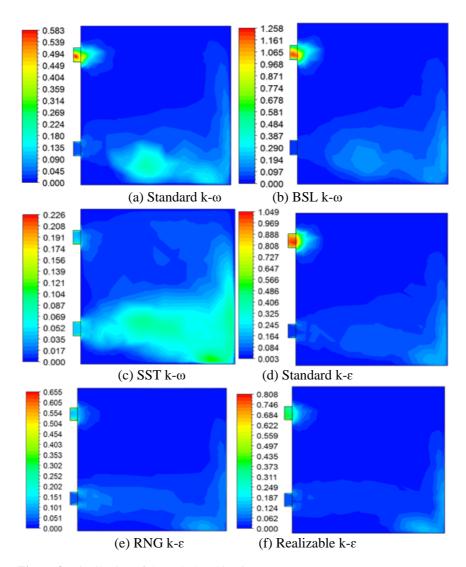


Figure 8. Distribution of the turbulent kinetic energy.

Indeed, the distribution of the turbulent kinetic energy in the four considered turbulence models affirms that the turbulence model presents a straight effect on the distribution of the turbulent kinetic energy. In fact, it has been observed that the maximum value of the turbulent kinetic energy is obtained in the hole outlet and it reaches $k=1.258~\text{m}^2.\text{s}^{-2}$ for the BSL k- ω turbulence model. However, this value reaches a low value, which is about $k=0.226~\text{m}^2.\text{s}^{-2}$, for the SST k- ω turbulence model.

4.5. Turbulent Viscosity

Figure 9 shows the distribution of the turbulent viscosity in the plane defined by x = 0.06 m and for the four turbulence models. According to these results, it can be seen that the turbulent viscosity presents a small value at the box inlet for all cases. However, the turbulent viscosity rises at the expulsion area which shown in the down hole of the system. The maximum values of the turbulent viscosity appear in the discharge area near the reverse wall. Otherwise, a peak value appears at the top hole of the box prototype due to the recirculation zone of the hot air in this region. By comparison of the obtained results, it has been observed a small effect of the different studied models on the distribution of the turbulent viscosity. In fact, the extension of the wake zone distinctiveness of the maximum values of the turbulent viscosity, obtained in the discharge area near the reverse wall, is more developed for the BSL k-ω turbulence model. Using this model, the maximum value of the turbulent viscosity reaches $\mu_t = 0.00192 \text{ kg.m}^{-1}.\text{s}^{-1}$ in the hole outlet. However, this parameter presents a low value equal to $\mu_t = 0.00032 \text{ kg.m}^{-1}.\text{s}^{-1}$ for the RNG k- ϵ turbulence model in the discharge area. In this case, the turbulent viscosity continues to decrease immensely in the outlet hole.

Conclusion

The present paper aims to investigate the impact of the turbulent model on the heat ventilation studied in a box prototype. Particularly, a computational study and an experimental validation have been developed to compare the standard k- ω , the SST k- ω , the BSL k- ω , the standard k- ε , the Realizable k- ε and the the RNG k- ε turbulence models. From the obtained results, it is noticed that the aerodynamic characteristics presents the same emergence nevertheless the

maximum values depend on the turbulence model. Particularly, it has been noted that the value founded with the standard $k\text{-}\omega$ tubulence model is nearest to the experimental data. This study tends to show that the standard $k\text{-}\omega$ turbulence model is the most efficient model to analyze the air flow in the box prototype. In the future, we suggest to extend this application with others geometrical arrangements.

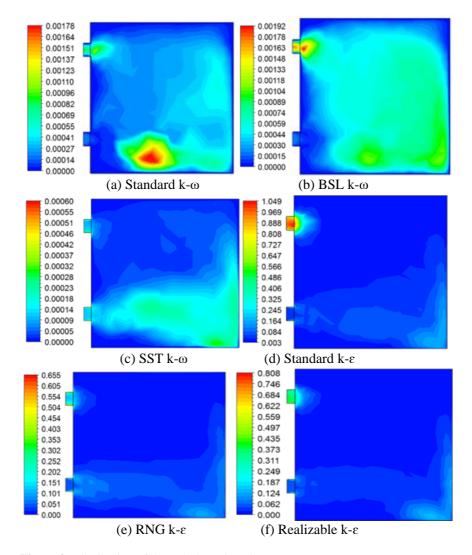


Figure 9. Distribution of the turbulent viscosity.

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